

Signal- \mathcal{LBC} and posttranslational oscillators

Chris Banks, Ian Stark (LFCS),
Daniel Seaton (SynthSys)



PEPA club, November 2013

In this talk I will

- give a brief overview of the Logic of Behaviour in Context (*LBC*)
- define the semantics of Signal-*LBC*
 - relative time
 - efficient data structures
 - (event precision)
- show how *LBC* is being used in a biochemical case study
 - posttranslational oscillator models
 - formulae for oscillation
 - inhibitor response
 - phase response

Part I

LBC

$\mathbf{F}\phi$ Eventually (**F**uture)

$\mathbf{G}\phi$ Always (**G**lobally)

$\mathbf{F}_{[0,t]}\phi$ Eventually within t

$\mathbf{G}_{[t,t']}\phi$ Always between t and t'

$Q \triangleright \phi$ Introducing $Q \implies \phi$

$\mathbf{G}_{[0,t]}(Q \triangleright \phi)$ At any time until t introducing $Q \implies \phi$

$\mathbf{F}_{[t,t']}(Q \triangleright \phi)$ At some time between t and t' introducing $Q \implies \phi$

F and **G** can be defined in terms of **U**:

$$\mathbf{F}_I\phi \equiv \top \mathbf{U}_I\phi$$

$$\mathbf{G}_I\phi \equiv \neg \mathbf{F}_I\neg\phi$$

Key rules in the semantics of \mathcal{LBC} :

$$P \models Q \triangleright \phi \iff (Q \parallel P) \models \phi$$

$$P \models \phi \mathbf{U}_I\psi \iff \exists t \in I, P(t) \models \psi \text{ and } \forall t' \in [0, t], P(t') \models \phi$$

Absolute or relative time depends on the semantics of $P(t)$:

- $P(t)$ begins at time $t \implies$ absolute
- $P(t)$ begins at time reset to zero \implies relative

Absolute time:

- time bounds refer absolutely to the time in the model
- original efficient algorithms for \mathcal{LBC} required this

Relative time:

- time bounds are relative to the parent modality
- consider $\mathbf{FG}_{[0,3]}\phi$.
- with relative time: “Eventually ϕ for at least 3 time units”
- properties like this are definitely useful for biochemistry.

The algorithmic landscape for \mathcal{LBC}

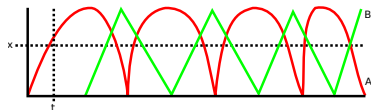
	Rel/Abs	Linear TL	Short-circuit
Naive	Both	×	✓
Dynamic	Abs	✓	×
Hybrid	Abs	✓	✓
Signal	Rel	✓	×

Part II

Signal- \mathcal{LBC}

(Maler & Nickovic, 2004)

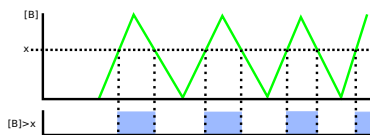
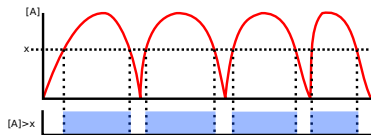
A trace (time series):



A formula:

$$\mathbf{F}_{[0,t]}((A > x) \vee (B > x))$$

Each proposition of the formula becomes a signal:



Signal combinators

\vee is the union of intervals:



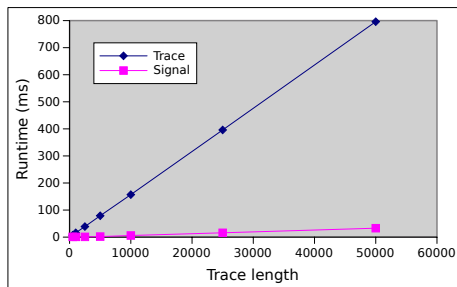
$F_{[a,b]}$ for a signal with intervals $[m, n)$ is the “positive Minkowski difference” of each interval:

$$\begin{aligned} & [m, n) \ominus [a, b] \cap \mathbb{R}_{\geq 0} \\ &= [m - b, n - a) \cap \mathbb{R}_{\geq 0} \end{aligned}$$



To compute a signal for $Q \triangleright \phi$, for now we:

- recalculate the trace at each original time-point with Q introduced
- signal represents the truth values of ϕ at each of these points
- this is essentially the same as in the old algorithms, and has the same worst-case time
- there is a better way (current work on sensitivity)



- Worst case for temporal fragment is much better!
- Worst case for full \mathcal{LBC} is comparable
 - lose short-circuiting, so slower in practical terms
 - but gain more useful relative time expressiveness
 - (improvements to come here)

Benefits of a signal semantics:

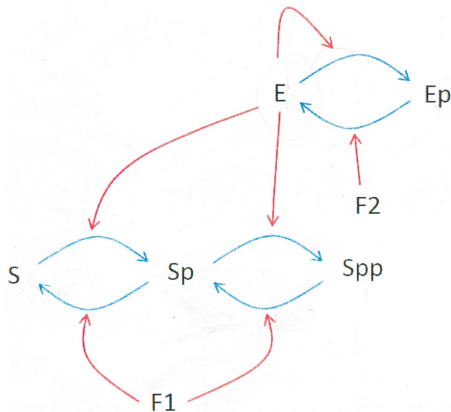
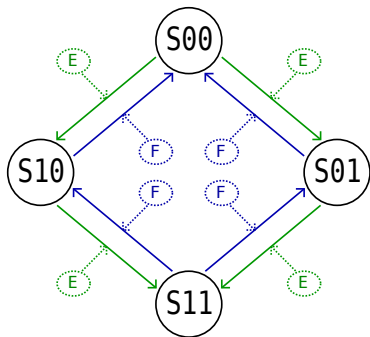
- gives an efficient relative time semantics
- actually more efficient for temporal fragment (compression)
- event detection could be used to generate signals directly
 - event precision
 - possibly even performance gain (no trace to signal conversion)

Limitations:

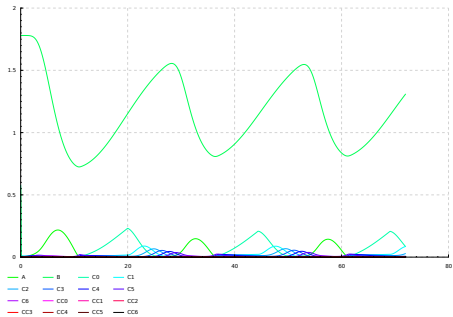
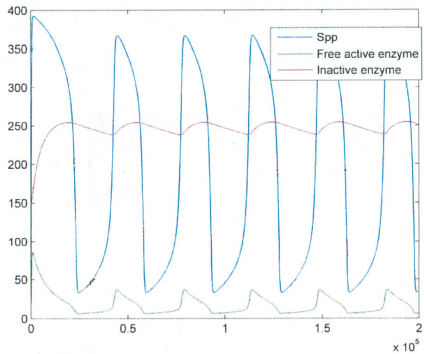
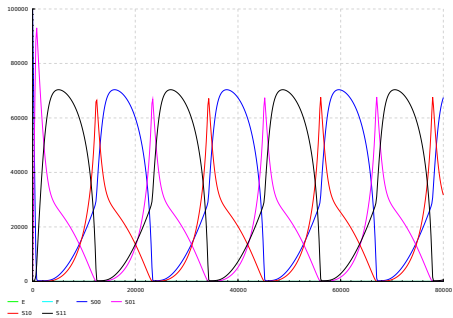
- doesn't readily short-circuit
- no improvement in worst-case time for full \mathcal{LBC}
 - dominated by solver calls

Part III

Posttranslational oscillators



- Jolley's model is candidate mechanism for a circadian PTO
- Seaton's model is novel oscillator mechanism based on auto-inhibition
- The Kai oscillator is a large, well studied model of the circadian clock mechanism in a cyanobacteria.



- Behaviour of coupled oscillators
 - previous talk (coupled Jolley PTOs)
 - hard to do with ODEs, easy with a high level language
 - pairing of each of the three types
 - chain of all three
- Comparison of behaviour between models
 - circadian clock behaviour vs. conjectured mechanisms
 - comparison by results of model checking
 - oscillation, inhibitor response, and phase response

I will show a selection of some of the more interesting properties we can formulate using *LBC*.

Oscillation:

$$PTO \models \mathbf{G}_{[0,t]}(\mathbf{F}_{[0,p]}([\mathcal{S}]' > 0) \wedge \mathbf{F}_{[0,p]}([\mathcal{S}]' < 0))$$

where $[\mathcal{S}]'$ is the first derivative of $[\mathcal{S}]$.

- until time t the concentration of \mathcal{S} is always, within time p , increasing then decreasing within time p
- oscillation with period at most p
- suitable for these models, but not a general formula for oscillation
- susceptible to noise, but again fine for these models

General oscillation using context:

$$PTO \models \mathbf{F}_{[p_1, p_2]}(\widehat{PTO} \triangleright (\mathbf{F}_{[0, s]} \mathbf{G}_{[0, t]} (|[S] - [\widehat{S}]| < \epsilon)))$$

where \widehat{PTO} is a copy of PTO , S is the species being observed, and \widehat{S} is the copy of S in \widehat{PTO} , and s is a maximum transient period before reaching limit cycle.

- if we introduce \widehat{PTO} after some period in $[p_1, p_2]$ then, within s , $[S]$ and $[\widehat{S}]$ will synchronise to within ϵ until t .
- a very succinct description of something that is non-trivial to code in, for example, MATLAB
- checking might be computationally intensive, but gives us general oscillation

So if 0_{sc} is one of these oscillation properties:

$$PTO1 \models PTO2 \triangleright 0_{sc}$$

and

$$PTO1 \models \mathbf{G}_{[0,c]}(PTO2 \triangleright 0_{sc})$$

where c is the end of the first cycle of $PTO1$.

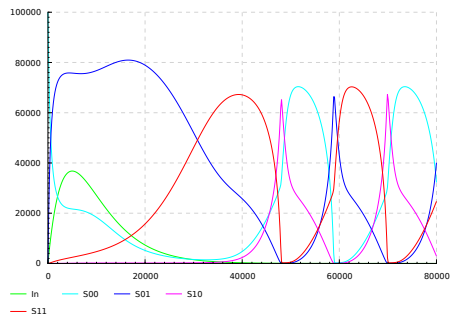
We can test that the coupled oscillators still oscillate, even when coupled in any phase.

Perturbation response:

$$PTO \models \mathbf{F}_{[0,t]}(P \triangleright \mathbf{F}_{[0,r]}([S] > pk))$$

- is some peak value pk ever exceeded under some perturbation P , within time t
- r is the max expected time of the peak after perturbation

Phase response:



- given a perturbation, at any point in the cycle, what is the effect on the phase of oscillation?
- biologists will plot a phase response curve, using a number of experiments
- but we can formulate some qualitative properties of phase response

Phase response:

$$PTO \models \widehat{PTO} \triangleright \mathbf{F}_{[c_1, c_2]}(P \triangleright (\mathbf{G}_{[t_1, t_2]}([\widehat{S}]' > 0 \implies \mathbf{F}_{[s_1, s_2]}[S]' > 0)))$$

- some perturbation P applied within $[c_1, c_2]$ will cause a forward phase shift $\in [s_1, s_2]$
- t_1 is a known max transient period after introducing P
- t_2 is a sensible max time to simulate for
- assumes we know the perturbed system still oscillates

- Signal- \mathcal{LBC} gives a relative time logic with reasonably efficient model checking.
- It is useful for checking biochemical properties.
- Although model checking might not be as computationally efficient as a hand-rolled solution it automates the process of implementation.
- Use of a high level language ($c\pi$) for defining models, a rich query language (\mathcal{LBC}), and model checking (CPiWB) simplifies the process of analysing coupled models with complex dynamics.